

Claims 1-21 have been cancelled.

22. (Currently amended) A swivel for an industrial robot, comprising:
two coaxial, mutually rotatable members and having a plurality of means for transferring operating and/or controlling media between the members, wherein said means are flexible hoses or cables between the members.

23. (Previously presented) The swivel according to claim 22, wherein the hoses or cables are elastically extensible.

24. (Previously presented) The swivel according to claim 23, wherein hoses or cables are spiral hoses or cables.

25. (Previously presented) The swivel according to claim 23, wherein the hoses or cables are connected to the members by means of quick-couplings.

26. (Previously presented) The swivel according to claim 22, wherein a cylindrical housing for enclosing the hoses or cables between the two members is provided.

27. (Previously presented) The swivel according to claim 22, wherein one of the members is a lower connection ring and the other member is a cover, the cover being connected to a central shaft, in relation to which the lower connection ring is journalled.

28. (Previously presented) The swivel according to claim 27, wherein the cover is connected to the central shaft by means of a quick-coupling.

29. (Currently amended) The swivel according to claim 27, wherein the lower connection ring and the cover are each provided with a plurality of through connection holes.

30. (Previously presented) The swivel according to claim 27, wherein the central shaft is arranged on a base plate.

31. (Previously presented) The swivel according to claim 22, wherein the mutual rotation between the two members is limited to no more than one full revolution.

32. (New) The swivel according to claim 27, wherein said flexible hoses or cables are connected generally axially to the central shaft when the rotatable members are in a non-rotated position.